

# JINWOO400S Tech. Specs. and Descriptions

TECHNICAL SPECIFICATIONS ~ JINWOO400S				
DESCRIPTION		UNITS	SPECIFICATIONS	
PRODUCT CODE	BY OEM	-	JINWOO400S ( <b>OPTIONAL 300Kgs Crane Winch</b> )	
MANUFACTURER	OEM	-	JINWOO SMC. CO. LTD.	
PERMISSIBLE MOUNTING VEHICLE	DAEWOO or HYUNDAI MOTORS	-	4x2, 220PS ENGINE, 14TONS GVW WITH 3,850MM WHEEL BASE	
PRODUCT  ( INCLUSIVE OF VEHICLE )	STOWED LENGTH	mm	7,475 ( <b>Compact for any roads</b> )	
	STOWED WIDTH	mm	2,205	
	STOWED HEIGHT	mm	3,400	
	WEIGHTAGE	Tons	≈13.0	
TELESCOPIC BOOM	No. of BOOMS	EA	8 ( ALL TELESCOPIC CHAIN TYPE )	
	CROSS SECTION	mm	18 EDGES (SPECIAL PATENTED DESIGN)	
	TYPE	-	PROPORTIONAL WITH MOMENT AUTO-LOCKING	
TURRET or TURNTABLE	ROTATION	DEGREE	STANDARD: 350° ( ±175° NON-CONTINUOUS )	
	TYPE	-	HYDRAULIC SLEWING BEARING WITH REDUCTION GEAR	
OUTRIGGER ( PATENTED X-A STYLE )	No. of BOOMS	-	TOTAL 3 ( 1 Fixed )	
	SLIDE STROKE LENGTH	mm	880 (FRONT & REAR)	
	MAX. OUTREACH	mm		6,950 (FRONT)
				8,525 (REAR)
OUTRIGGER JACKS	STROKE LENGTH	mm	860 (FRONT) / 740 ( REAR )	
STEEL PLATFORM  or  FRP INSULATED BASKET	F.R.P BASKET	mm	1,280(L)*1,100(H)*850(W)(for 2 workmen)	
	F.R.P INSULATION	Volts	20,000	
	ALUMINIUM	mm	3,230(L)*1,030(W)*1,100(H) ( for 2 workmen )	
	TYPE	-	HYDRAULIC ; SELF-LEVELING	
PROPORTIONAL PVG32 VALVE CONTROLS	ROTATION	DEGREE	360° CONTINUOUS ( Max. ±720° ) USING RING GEAR	
	BASIC TYPE	-	MANUAL LEVER ( OUTRIGGER AND BOOM )	
	REMOTE CONTROL	-	PORTABLE WIRELESS ( FOR UPPER CONTROLS )	
MAX. WORKING HEIGHT		M	40 (38M TO FLOOR OF BASKET )	
MAX. OUTREACH (REAR & SIDES)		M	<b>WITHOUT</b> KOREAN VEHICLE: 23 @ 100Kg; 17.5 @ 500Kg <b>WITH</b> KOREAN VEHICLE: 25 @ 100Kg; 19 @ 500Kg	
MAX. WORKING LOAD (PAYLOAD)		Kgs	500 for ALUMINIUM PLATFORM ~ Std. design 250 for FRP BASKET ~ <b>Optional</b> <b>SPECIAL 500KG PAYLOAD ~ Optional</b>	
HYDRAULIC OIL TANK CAPACITY		Ltrs.	160	
SAFETY DEVICES		-	RELIEF & COUNTER BALANCE VALVES, PROPORTIONAL CONTROL VALVE, PLATFORM SAFE ANGLE CONTROL VALVE, PILOT CHECK VALVE, OVERTURNING ALARM, BOOM OVER EXTENSION ALARM (OPTIONAL: AUTOMATIC CUT-OFF SAFETY SYSTEM), DISPLAY MONITOR, PAYLOAD & BOOM ANGLE LIMITER, <b>OUTRIGGER POSITION BASED WORK AREA AUTOMATIC CUT-OFF SYSTEM</b> etc...	

Note: Technical Specifications are bound to change without prior notification.



TRANSPORT DIMENSIONS – MOST COMPACT IN THIS SERIES.

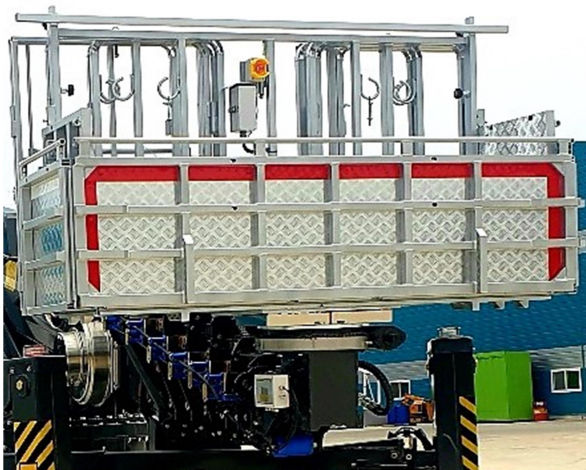


READY-FOR-DELIVERY PRODUCT IN READY-TO-OPERATE CONDITION.



EASILY ACCESSIBLE OPERATOR'S GROUND CONTROLS STATION(WITH HYDRAULIC CONTROL LEVERS AND ENGINE CONTROL SYSTEM) ON TURRET.

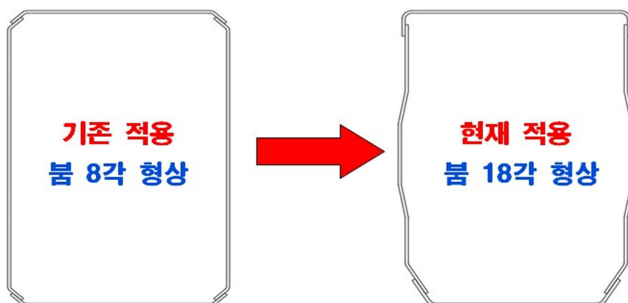
\* POSSIBLE TO PROVIDE WITH ERGONOMIC CABIN AND AIR-CONDITIONER \*



LIGHTER WEIGHT YET STRONGER EXTENDABLE (UPTO3.25M) ALUMINIUM PLATFORM WITH 500KG PAYLOAD CAPACITY.

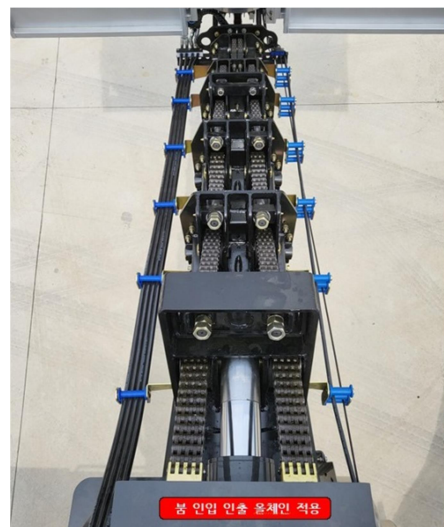


FULLY COVERED BASE FRAME DECKS FOR SAFE PROTECTION OF THE ELECTRONIC SYSTEM AS WELL SPACIOUS TOOLS BOX.



단면 계수 증대로 좌우 흔들림 최소화

TRADITIONAL 8 EDGES UPGRADED TO 18EDGES FOR REDUCING BOOM BENDING



FULL-CHAIN SYSTEM FOR LIFELONG SERVICE WITH LEAST MAINTENANCE



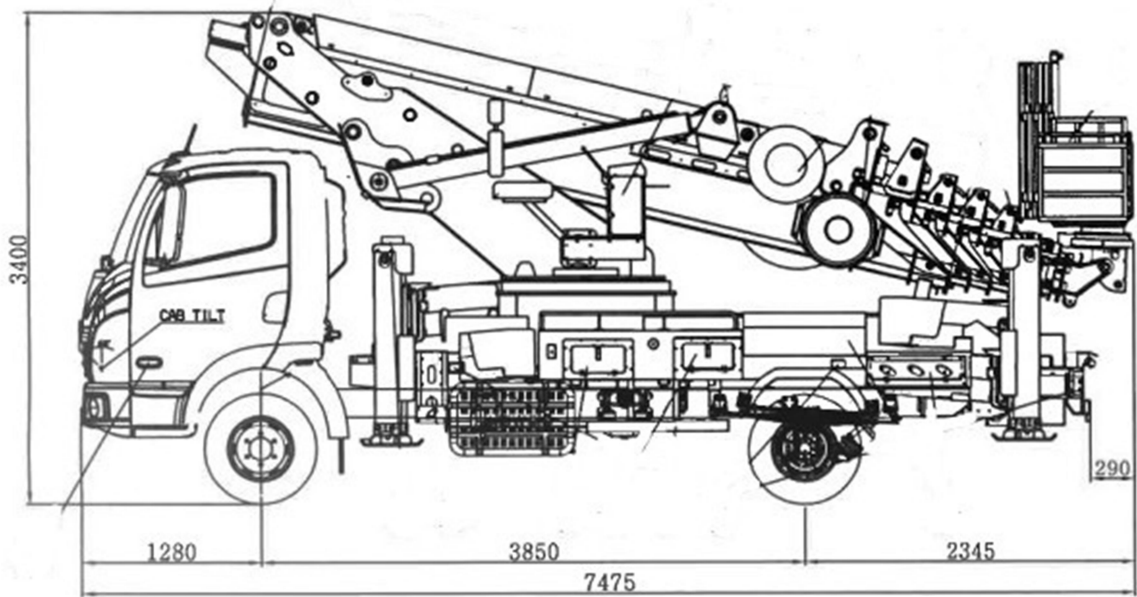
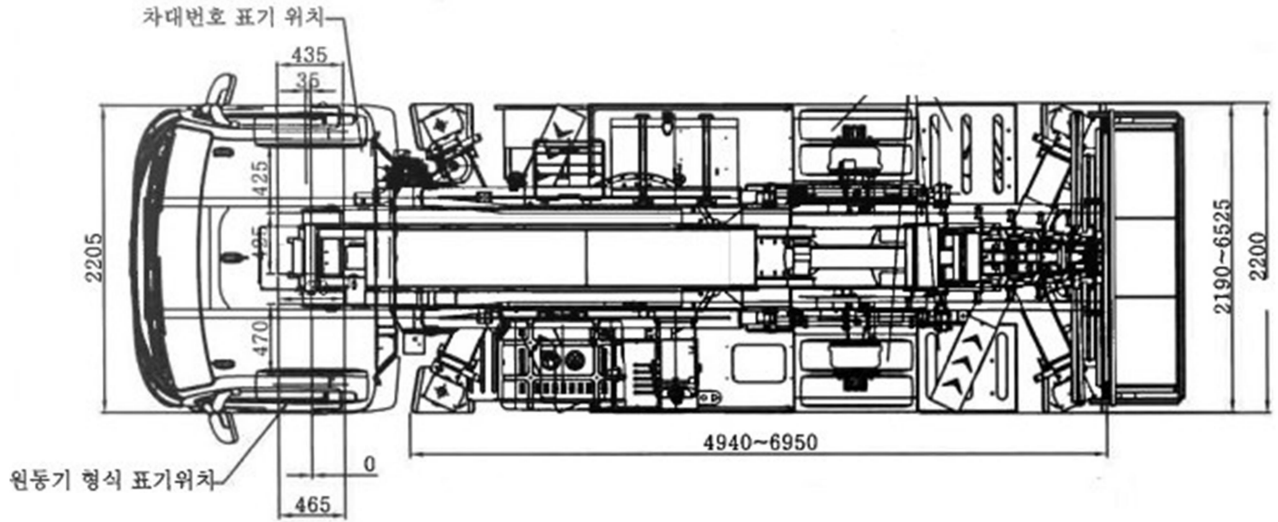
STRAIGHT BOOMS ( WITHOUT BENDING ) AT MAX., HEIGHT AND ANGLE.



MODELS IN STOCK FOR SALE.

ASSEMBLY DRAWING

외관도  
(SMC-B8S3D130S22)

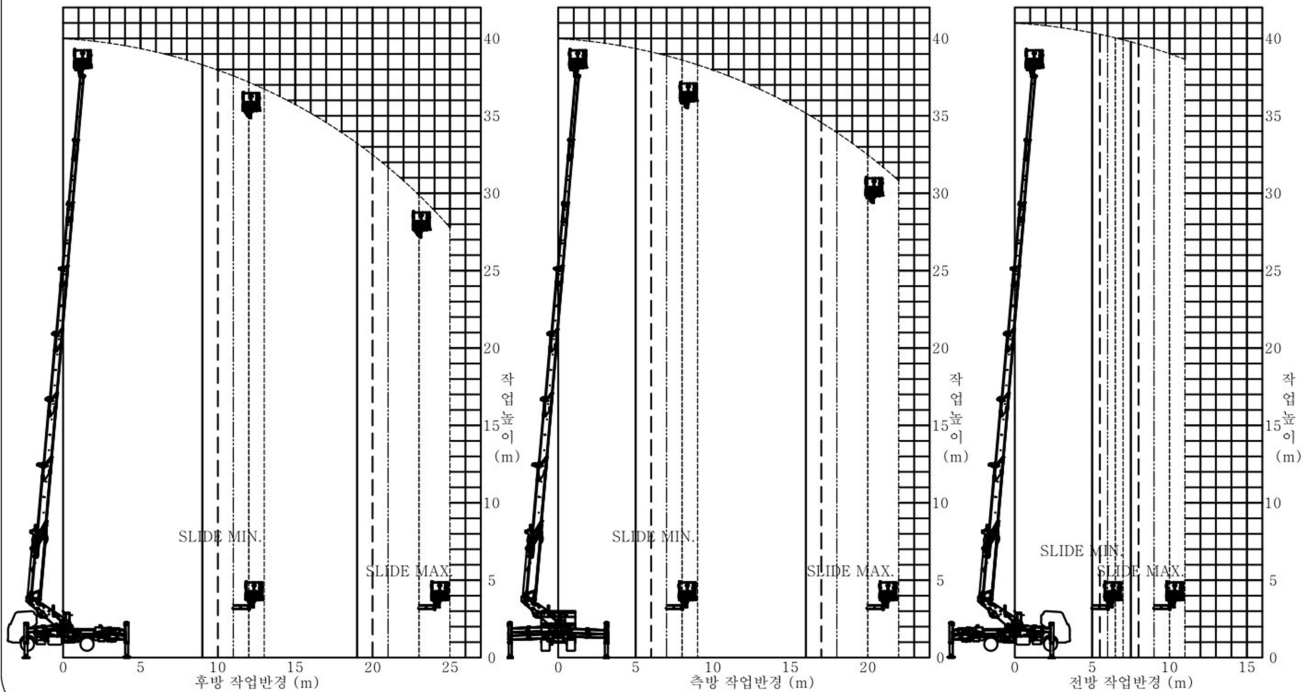
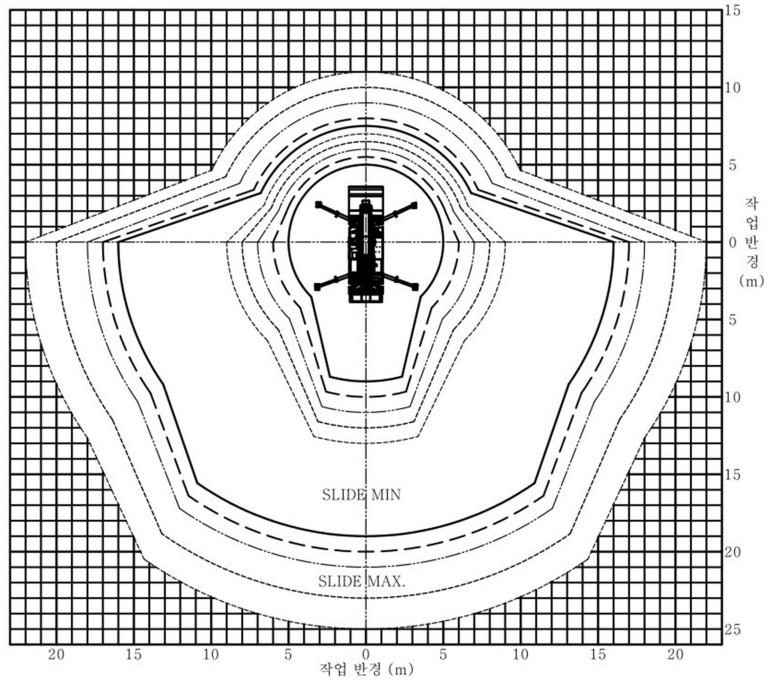


# WORK AREA DRAWING

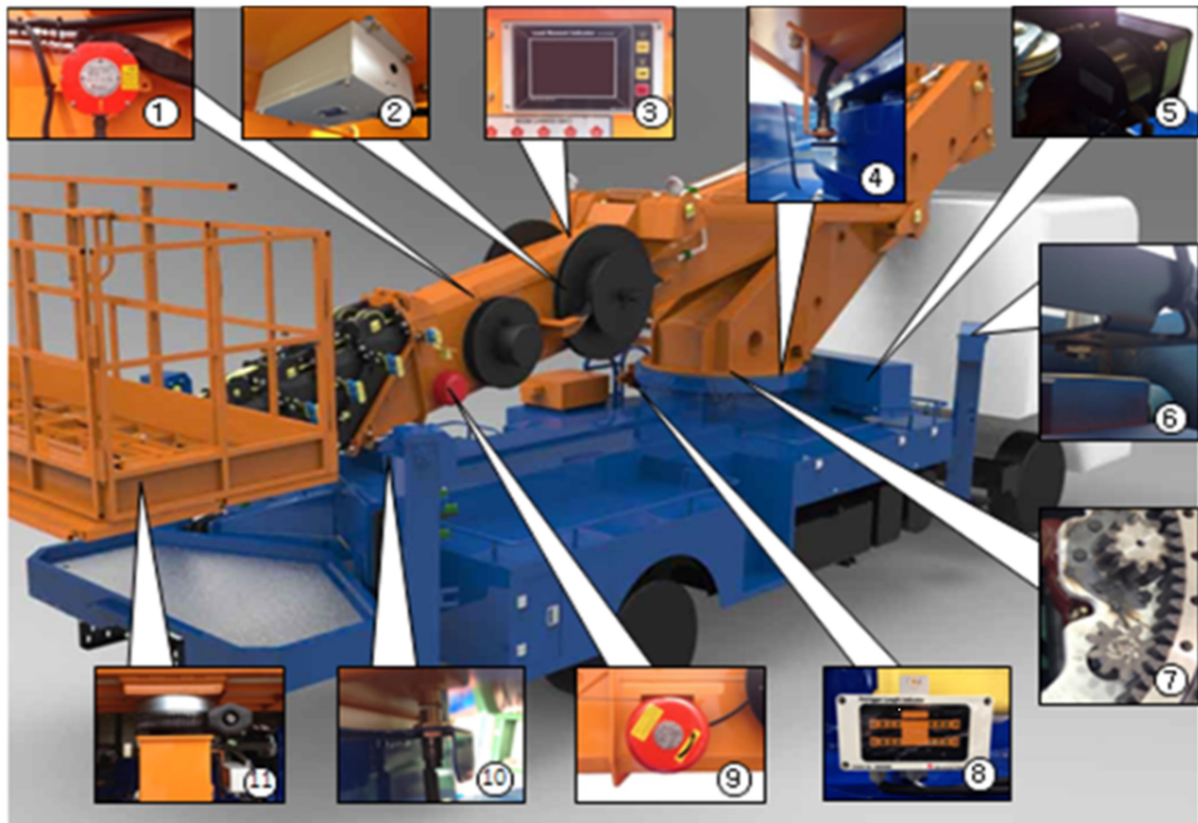
## JINWOO 400S 작업반경도

하중별 반경표시	선형식	하중
———	500kg	
- - - - -	400kg	
· · · · ·	300kg	
· · · · ·	200kg	
· · · · ·	100kg	

- \* 슬라이드 확장 단계별 반경은 슬라이드 MIN/MAX 반경 사이에서 슬라이드 확장상태에 따라 변경, 규제됩니다.
- \* 슬라이드 미확장시에는 볼 최대인출이 불가능합니다.
- \* 상기의 제한은 안전과 성능향상을 위하여 변경될 수 있습니다.



## Mechatronic Automatic Cut-off System - AML(Auto Moment Limiter) System



- ① **Boom angle sensor** : Controls work radius by checking boom angle.
- ② **Controller of safety system** : Controls emergency situations and normal operations by receiving signal from different Sensors.
- ③ **Display Monitor** : Displays different operations parameters and also status warning on touch-screen color monitor, along with audio alarm in case of emergency.
- ④ **Turret Swing sensor** : It indicates the swing angle of the turret and boom and controls the swing within the design permitted range. It will automatically cut-off the rotation of turret and boom.
- ⑤ **Outrigger Slide length sensor** : Controls work radius by detecting slide's length and position to avoid tilting of the vehicle.
- ⑥ **Anti-Tilt sensor** : Its Secondary safety system. Warns the operator with high-audio alarm if any or all of the outrigger jacks are not touching the ground and if they lift from the ground when boom operations are performed.
- ⑦ **Rotation detecting Encoder** : Detects the rotation angle of the Turret and Boom.
- ⑧ **Outrigger Jack Position Indicator** : It shows 3 different positions of the Outrigger Jacks using the Slide length sensor.
- ⑨ **Boom length sensor** : Controls the safe extension of boom and limits it within the permissible design limit.
- ⑩ **Boom-Outrigger interlock sensor** : Its Primary safety system. Ensures that Outrigger and Boom/Basket operations cannot be performed together but either of the one is only possible.
- ⑪ **Load cell(Weight sensor)** : Controls the work area and cuts-off all Boom as well as platform operations if over loaded by detecting payload in platform.



**OPTIONAL: AUTOMATIC MOMENT LIMITING(AML) MECHATRONIC CONTROL SYSTEM;  
PROVIDED WITH THE DESCRIPTIONS.**

